Abstract. The vadose zone is a highly interactive heterogeneous system through which water enters the subsurface system by infiltration. This paper details the effects of simulated plant exudate and soil component solutions upon unstable flow patterns in a porous medium (ASTM silica sand; US Silica, Ottawa, IL, USA) through the use of two-dimensional tank light transmission method (LTM). The contact angle ($\theta$) and surface tension ($\gamma$) of two simulated plant exudate solutions (i.e., oxalate and citrate) and two soil component solutions (i.e., tannic acid and Suwannee River natural organic matter, SRNOM) were analyzed to determine the liquid–gas and liquid–solid interface characteristics of each. To determine if the unstable flow formations were dependent on the type and concentration of the simulated plant exudates and soil components, the analysis of the effects of the simulated plant exudate and soil component solutions were compared to a control solution (Hoagland nutrient solution with 0.01 M NaCl). Fingering flow patterns, vertical and horizontal water saturation profiles, water saturation at the fingertips, finger dimensions and velocity, and number of fingers were obtained using the light transmission method. Significant differences in the interface properties indicated a decrease between the control and the plant exudate and soil component solutions tested; specifically, the control ($\theta = 64.5^\circ$ and $\gamma = 75.75$ mN m$^{-1}$) samples exhibited a higher contact angle and surface tension than the low concentration of citrate ($\theta = 52.6^\circ$ and $\gamma = 70.8$ mN m$^{-1}$). Wetting front instability and fingering flow phenomena were reported in all infiltration experiments. The results showed that the plant exudates and soil components influenced the soil infiltration as differences in finger geometries, velocities, and water saturation profiles were detected when compared to the control. Among the tested solutions and concentrations of soil components, the largest finger width (10.19 cm) was generated by the lowest tannic acid solution concentration (0.1 mg L$^{-1}$), and the lowest finger width (6.00 cm) was induced by the highest SRNOM concentration (10 mg L$^{-1}$). Similarly, for the plant exudate solutions, the largest finger width (8.36 cm) was generated by the lowest oxalate solution concentration (0.1 mg L$^{-1}$), and the lowest finger width (6.63 cm) was induced by the lowest citrate concentration (0.1 mg L$^{-1}$). The control solution produced fingers with average width of 8.30 cm. Additionally, the wettability of the medium for the citrate, oxalate, and SRNOM solutions increased with an increase in concentration. Our research demonstrates that the plant exudates and soil components which are biochemical compounds produced and released in soil are capable of influencing the process of infiltration in soils. The results of this research also indicate that soil wettability, expressed as $(\cos \theta)^{1/2}$, should be included in the scaling of the finger dimension, i.e., finger width, when using the Miller and Miller (1956) scaling theory for the scaling of flow in porous media.
1 Introduction

Infiltration of water in soil is a fundamental element of the hydrologic cycle (Horton, 1933). The infiltration process controls the existence of water and life at the soil–atmosphere interface, by controlling soil moisture (Rodriguez-Iturbe et al., 1999) and supporting vegetation (Liang et al., 1994). In addition to controlling soil moisture and plant life, soil controls deep drainage of infiltrated water, its rate, and its quality. The infiltration process is impacted by the physicochemical properties and biological activities that occur in the unsaturated zone of the soil (vadose zone), as well as human activities and the climate (Glass et al., 1991). Consequently, understanding the movement of water in soils is particularly valuable in terms of groundwater recharge and contaminant loading.

In general, water flow and contaminant transport in soil are heterogeneous (Bien et al., 2013; Wang et al., 2006). Preferential flow, which concentrates flow to a small fraction of a porous media (Hendricks and Flury, 2001), has been the subject of numerous studies (e.g., Andreini and Steenhuis, 1990; Flury et al., 1994; Gerke et al., 2010; Glass et al., 1989a, b, c, d; Kung, 1990a; Ritsema et al., 1993; Simunek et al., 2003). There are several mechanisms that have been identified as contributors to preferential flow processes, such as macropore flow (e.g., connected and disconnected macropores, cracks, earthworm burrow, root channels) (Beven and Germann, 2013; Bouma and Dekker, 1978), fingered flow (i.e., wetting front/gravity-driven instability or “fingers”) (Glass et al., 1989c, d; Wang et al., 2003a), and funnel flow (e.g., layering or textural interfaces) (Kung, 1990a, b). Bypassing of the soil matrix during preferential flow produces the rapid transport of solutes and particles, thereby increasing risks to groundwater by reducing opportunities for natural attenuation of contaminants such as pesticides, nutrients, metals, pathogens, radionuclides, antimicrobials, and nonaqueous phase liquids (NAPLs) (Darnault et al., 2003, 2004; Di-Carlo et al., 2010; Engelhardt et al., 2015; Jarvis et al., 2016; Kay et al., 2004; Kim et al., 2005; Nimmo, 2012; Uuyusur et al., 2010, 2015). Therefore, understanding environmental factors that might increase the occurrence of preferential flow is of key importance. In this work we are specifically concerned about whether the presence of natural biologic (i.e., root) exudates contributes to the onset of unstable fingered flow.

The process of infiltration in soils is the particular interaction of the dynamics of fluid interfaces and flow in porous media, where infiltration is an overall downward movement of water into dry unsaturated soils, causing the formation of a gas–water interface, known as the “wetting front.” The nonlinear behavior of the relationship between the soil hydraulic properties and the soil moisture content sets the conditions for the development of the wetting front, but the classification of the wetting front propagation as stable or unstable is determined by the interplay between the two forces, capillarity and gravity (Cueto-Felgueroso and Juanes, 2008; Wallach et al., 2013). During a stable infiltration process leading into a homogeneous porous medium under a steady state flux condition at the surface, a stable wetting front moves downward as it is driven by gravity and stabilized by the surface tension resulting from capillary forces present in the porous medium. While in an unstable infiltration process leading into a homogeneous porous medium under steady state flow, it is when the gravity and capillary forces are nearly equal but opposite in magnitude that small irregularities, such as small heterogeneities (which are inevitable, even in a practically homogeneous medium), will lead to the condition where gravity dominates. At that point the unstable wetting front will occur and “fingers” are generated (Glass et al., 1989a, b, c; Hill and Parlange, 1972; Kapoor, 1996; Peck, 1965; Selker et al., 1992a, b). Once these fingered flow phenomena are generated, the flow area is decreased compared to that of the wetting front, and the flux velocities of the fingers increase tremendously (Wallach et al., 2013). Peck (1965) was the first to describe the formation of “tongues” of infiltrating water in sand columns and the entrapment of air below the wetting front. Hill and Parlange (1972) conducted the first systematic experiment to investigate the phenomenon of wetting front instability. The role and importance of fingered flow in contaminant transport has been demonstrated with several cases of groundwater contamination (e.g., Hillel, 1987; Steenhuis et al., 1990).

The nonlinearity of the governing equations for unsaturated flow through porous media makes a theoretical analysis of water movement in soils and wetting front instability in soils most challenging (Buckingham, 1907; Richards, 1931). Infiltration theories and the development of mathematical solutions to solve the problem of flow in porous media have been the subject of much research, most particularly the seminal works of John Philip (Philip, 1969, 1975) and Jean-Yves Parlange (e.g., Parlange, 1971a, b, c, 1972a, b). Further, Saffman and Taylor (1958) and Chouke et al. (1959) concluded that the development of wetting front instability resulted from unsaturated flow. Wetting front instability and resultant fingering flow phenomena can occur due to an increase in hydraulic conductivity with depth (Hill and Parlange, 1972; van Ommen et al., 1989), a decrease in soil wettability with depth (Hill and Parlange, 1972; Hillel, 1987; Philip, 1975; Raats, 1973), water repellency (Dekker and Ritsema, 1994; Ritsema et al., 1993; Ritsema and Dekker, 1994), a redistribution of infiltration after the end of rainfall or irrigation (Philip, 1975), air entrapment (Peck, 1965; Philip, 1975; Raats, 1973; Wang et al., 1998), and nonponding rainfall (Pendexter and Furbish, 1991; Raats, 1973; J. S. Selker et al., 1992).

In addition to these theoretical analyses, numerous experimental studies have been undertaken to elucidate the process of infiltration in soils and the instability of wetting front propagation. The process of infiltration in soils and the instability of wetting fronts has been studied primarily in two-
dimensional tanks where it is possible to image the generation of a two-dimensional fingered flow (e.g., Bauters et al., 2000a; DiCarlo, 2004; Glass et al., 1989a, c, d, Selker et al., 1992a, b; J. S. Selker et al., 1992), and more recently using geo-electrical imaging (Ganz et al., 2014; Liu and Moody, 2012) and ground-penetrating radar (Mangel et al., 2012, 2015). Laboratory experiments designed to examine the infiltration process in homogeneous porous media have confirmed the ubiquitous formation of fingered flow (Bauters et al., 2000b; Glass et al., 1989d; Selker et al., 1992a; Wang et al., 2003b, 2004). Experimental observations have also demonstrated that the fingers that develop the most rapidly will convey most of the flow, while the other initial fingers will be quenched (Glass et al., 1989d; Selker et al., 1992b). The fully formed fingers generated by gravity-driven flow behave like traveling waves (i.e., they have constant shape and velocity), and the water saturation profile of the fully formed fingers exhibit a region of high water saturation (i.e., overshoot) directly behind the wetting front, followed by another region of drainage where the water content in the finger decreases to a lower and uniform water saturation, known as the finger tail (DiCarlo, 2004; Glass et al., 1989a; Liu et al., 1994; Selker et al., 1992b). This increase in water saturation at the fingertip, “saturation overshoot,” causes a rise in pressure and creates a positive matric potential gradient on top of the fingertip (DiCarlo et al., 1999; Geiger and Durnford, 2000). This rise in pressure also increases the delineation between the wet and dry porous media at the edge of the wetting front and facilitates the propagation of the wetting front. The length of the saturation overshoot (i.e., the fingertip length) has been deemed a function of the wetting front velocities (DiCarlo, 2004; Wallach et al., 2013). Further details on theoretical and experimental research on wetting front instability can be found in extensive reviews (Assouline, 2013; Glass and Nicholl, 1996; De Rooij, 2000; Xiong, 2014).

The rhizosphere is an important component of the vadose zone and is specifically defined as the narrow region of soil that is directly influenced by plant roots themselves and by the root secretions (Hinsinger et al., 2009; McCully, 1999; Passioura, 1988; Read et al., 2003). It has been estimated that about 40% of the precipitation on earth transitions through the rhizosphere (Bengough, 2012). The rhizosphere has a deep effect on hydrologic processes (Benard et al., 2016), and its interactions in the soil system not only involve the physical effects stemming from soil and root dynamics but also include biochemical effects from the compounds that the roots of a plant can exude from their root tips (Benard et al., 2016; Gregory, 2006; Hinsinger et al., 2009).

There are two main biochemical compounds produced by the plant roots: mucilage and exudates. Mucilage is a viscous substance composed mainly of polysaccharides and some phospholipids (Guinel and McCully, 1986; McCully and Boyer, 1997; Read et al., 2003) as well as to control the water repellency of the rhizosphere (Carminati, 2012; Carminati et al., 2010; Moradi et al., 2012). Root exudates comprise mostly sugar, amino acids, and organic acids and are exuded primarily from the root tips (Carvalhais et al., 2011; McCully, 1999; Passioura, 1988; Read et al., 2003). These exudates play a key role in keeping the contact between the roots and soil particles (Walker et al., 2003), the modulation and mobilization of the nutrients (Cakmak et al., 1998; Carvalhais et al., 2011; Wang et al., 2008), and the maintenance of the rhizosphere hydraulic properties (Ahmed et al., 2014) by providing a large water-holding capacity (McCully and Boyer, 1997), enhancing the movement of water in dry soil, and enabling the roots to get water from dry soils (Ahmed et al., 2014; Zarebanadkouki et al., 2016). Individual exudates have specific nutrients (i.e., phosphate, nitrate, potassium) that they are designed to extract from the soil. This unique chemistry thus increases the solubility of the sought-after nutrients to ease the uptake by the plant. In this regard, the exudates act as surfactants within the subsurface by lowering the surface tension and contact angles of the soil pore water, enhancing the wettability and reducing the suction and energy needed for the plant to extract what is needed (McCully, 1999; Passioura, 1988; Read et al., 2003).

The plant root growth in soil is constrained, however, as water, air, and nutrient resources are scarce and spatially and temporally heterogeneously available in soil (Hinsinger et al., 2009). Plants have evolved various adaptive strategies to adapt advantageously to the environment they encounter, including to access these resources. Hydromechanic analyses of soil and water interactions in the rhizosphere have demonstrated that rhizodeposits (i.e., mucilages and exudates) induce water potential gradients near the roots and therefore increase nearby soil moisture (Carminati et al., 2010; Gardner, 1960; Ghezzehei and Albalasmeh, 2015; Moradi et al., 2011; Young, 1995). As the water potential decreases near the root to produce a concurrent decrease in soil water content, water moves from the bulk soil to the root surfaces. Although the effect of root exudates on soil structure and aggregation has been well established (e.g., Alami et al., 2000; Czarnes et al., 2000; Ghezzehei and Albalasmeh, 2015; Kaci et al., 2005; McCully, 1999; Watt et al., 1994), research on the effect of the rhizodeposits (i.e., mucilages and exudates) on the soil–water relationship and water dynamics in the rhizosphere is very limited. This is a crucial knowledge gap in terms of the biogeochemical influences on the hydrologic processes occurring in the rhizosphere, as stated by Bengough (2012), particularly the effect that root exudates have on the nonequilibrium dynamics of interfaces and flow in porous media. Carminati et al. (2016) recently analyzed the rhizosphere processes to more thoroughly elucidate the system, with a particular focus on determining the role of mucilage in root water uptake. They found that wet mucilage enhances fluid transport, but when dry, the mucilage causes hydrophobic tendencies in the rhizosphere (Carminati et al., 2016). From this analysis they determined a need for new technology and
sensor applications to gain a full and detailed understanding of the rhizosphere, regardless of the new methodologies in development for imaging these systems and understanding the plants themselves. 

The objective of this study was to investigate the influence of various plant exudates (citrate and oxalate) and soil constituents (tannic acid and Suwanee River natural organic matter) on soil infiltration, particularly wetting front instability and fingered flow in unsaturated porous media. A Hoagland nutrient solution (HNS) with 0.01 M NaCl (NaCl and fingered flow in unsaturated porous media. A Hoagland nutrient solution (HNS) with 0.01 M NaCl (NaCl + HNS) solution was used as a control, as these solution compounds are used to simulate the nutrients a plant needs to survive, and these simulated compounds are also present in the rhizosphere. By utilizing plant exudate and soil constituent solutions, the physical effects of plant root interaction with soil infiltration processes and porous media spatial characteristics, such as heterogeneity and structure, were removed. Only the interactions between the physicochemical properties of the infiltrating water, the porous media properties, and the flow dynamics were analyzed for an independent determination of the individual constituent solution effects on the soil infiltration processes that were in the form of wetting front instability and fingered flow phenomena. The fluid properties were quantified by measuring contact angle and surface tension. The dynamics of interfaces in porous media – gas–liquid and solid–liquid interfaces – under the impact of various biochemical compounds were monitored via visualization. Utilizing the imaging technique of the light transmission method (LTM) that allows the visualization of fluid content and flow in porous media with high spatial and temporal resolution (Darnault et al., 1998, 2001; Niemet and Selker, 2001; Weisbrod et al., 2003), we studied the effects of several isolated organic compounds typically found in the rhizosphere that were dispersed as artificial rainfall and infiltrated under unsaturated conditions a homogenous sand porous medium on the wetting front stability and fingered flow phenomena in a two-dimensional tank. Ultimately, our understanding of the influence of these isolated plant exudates and soil constituents upon these infiltration processes and water saturation distribution within the porous medium is a significant step toward fully elucidating the range of interactions controlling flow within the rhizosphere.

2 Materials and methods

2.1 Simulated constituent solution preparation

In order to reduce the number of active variables present in this work, solutions of simulated plant exudates and soil components were used rather than living plants and soil. A Hoagland nutrient solution with 0.01 M NaCl (NaCl + HNS) was used as a control to simulate the nutrients required by a plant to survive in a sandy porous medium. The HNS was created by combining the components listed in Table 1 with 970 mL of ultrapure deionized (DI) water (18.2 MΩ·cm, Millipore Corporation, Billerica, MA) with NaCl (lot number: 2954C512, VWR Analytical BDH®, Radnor, PA) subsequently added to bring the solution to 0.01 M NaCl. These steps are based on the method developed by Amon and Hoagland in 1940. Two plant exudates – sodium citrate (S1804-500G, Sigma-Aldrich, Lake Cormorant, MS), and sodium oxalate (lot number: P17A014, Alfa Aesar, Ward Hill, MA) – and two soil components – Suwanee River natural organic matter (SRNOM, RO isolate, 2R101N, International Humic Substances Society, St. Paul, MN) and tannic acid (lot number: MKBV0516V, Sigma-Aldrich, Lake Cormorant, MS) – were used to create the solutions tested in this work. Using NaCl+HNS as a base solution, different concentrations of the constituents were created to simulate a range of potential concentrations, a list of which is provided in Table 2. These concentrations were categorized based on amounts naturally found in the environment (Jones, 1998; Strobel, 2001; Wagoner et al., 1997).

2.2 Solution characterization

A Kruss Easy Drop (FM40Mk2, Kruss Gmbh, Germany) was used to obtain the contact angle and surface tension with 5 µL of the various experimental solutions deposited on a 24 × 60 mm micro cover glass (CAT No. 4404-454, VWR, Radnor, PA) for the contact angle analysis. The drop shape analysis software (Kruss Gmbh, Germany) was used with the following settings: contact angle profile defined with circle fitting, drop type set as sessile drop, and sub-type set as normal. Images and data were collected every 30 s for 3 min for both the contact angle and surface tension data. The Kruss Easy Drop DSA1 internally computes the contact angle of a drop using the Young equation (Young, 1805):

$$\sigma_s = \gamma_{sl} + \sigma_1 \cdot \cos(\theta),$$  \hspace{1cm} (1)

where $\sigma_s$ is the solid surface tension, $\sigma_1$ is the liquid surface tension, $\gamma_{sl}$ is the interfacial tension between the phases, and $\theta$ is the contact angle. It also calculates the surface tension of pendant drops using the Young–Laplace equation (Laplace, 1806; Young, 1805):

$$\Delta P = \sigma \left( \frac{1}{r_1} + \frac{1}{r_2} \right),$$  \hspace{1cm} (2)

where $\Delta P$ is the difference in pressure of the inside and outside of the droplet, $r_1$ and $r_2$ are the principle radii of the droplet, and $\sigma$ is the surface tension. By using the characteristic shape and size of the droplets, the equipment can determine the surface tension of the droplet. These variables on a stable solution droplet collected at 90 s are illustrated in Fig. 1. Contact angle and surface tension measurements for all solutions were tested in triplicate with the averages and associated standard deviations presented in this work (Table 3). The surface tension measurements were obtained by
Table 1. Composition of Hoagland nutrient solution; recipe followed from Arnon and Hoagland (1940).

<table>
<thead>
<tr>
<th>Main solution</th>
<th>Amount in volume (mL)</th>
<th>Chemical</th>
</tr>
</thead>
<tbody>
<tr>
<td>(creates 1 L of solution)</td>
<td></td>
<td>Calcium nitrate tetrahydrate</td>
</tr>
<tr>
<td>10</td>
<td>0.5 M Ca(NO$_3)_2$</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>0.5 M KNO$_3$</td>
<td>Potassium nitrate</td>
</tr>
<tr>
<td>4</td>
<td>0.5 M MgSO$_4$</td>
<td>Magnesium sulfate</td>
</tr>
<tr>
<td>2</td>
<td>0.5 M KH$_2$PO$_4$</td>
<td>Potassium dihydrogen phosphate</td>
</tr>
<tr>
<td>2</td>
<td>Micronutrient Solution</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Micronutrient solution</th>
<th>Amount in mass (g)</th>
<th>Chemical</th>
</tr>
</thead>
<tbody>
<tr>
<td>(creates 500 mL of solution)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.43</td>
<td>H$_3$BO$_3$</td>
<td>Boric Acid</td>
</tr>
<tr>
<td>0.9</td>
<td>MnCl$_2$</td>
<td>Manganese (II) chloride</td>
</tr>
<tr>
<td>0.11</td>
<td>ZnSO$_4$</td>
<td>Zinc sulfate concentrate</td>
</tr>
<tr>
<td>0.04</td>
<td>CuSO$_4$</td>
<td>Copper (II) sulfate</td>
</tr>
<tr>
<td>0.1</td>
<td>(NH$_4$)$_6$Mo$<em>7$O$</em>{24}$</td>
<td>Ammonium molybdate</td>
</tr>
<tr>
<td>0.28</td>
<td>FeSO$_4$</td>
<td>Iron (II) sulfate heptahydrate</td>
</tr>
<tr>
<td>0.3</td>
<td>EDTA</td>
<td>Edetic acid</td>
</tr>
</tbody>
</table>

Figure 1. Visual of the drop shape analysis of (a) a contact angle and (b) the surface tension pendant drop using the Kruss Easy Drop. The images are of the control solution (HNS + HNS) taken at 90 s. Figure is based off of figures appearing in the *Kruss User’s Manual* (Kruss, 2004).

suspending the solution as a drop in an open-air environment from a 2 mm diameter needle point. The software was configured with the following settings: drop information with a needle diameter of 2 mm, a tip level (pixels) of 80, an assumed liquid drop density of 0.9975 g cm$^{-3}$, an embedding phase of 0.0012, a magnification factor (pixels mm$^{-1}$) of 79.827, and an aspect ratio of 1. A statistical analysis was done for the contact angle and surface tension measurements utilizing a t test using JMP Pro 12 from SAS.

2.3 Light transmission method

Developed by N. T. Hoa, the LTM was first used as a rapid, inexpensive method for the visualization of flow in 2-D systems (Hoa, 1981), and has since been expanded for use in water–air, oil–water, and water–oil–air systems. The methods used in this work adhere to the methods developed by Darnault et al. (2001, 1998). The LTM works through the illumination of a thin section of porous media (i.e., a 1 cm thick section of silica sand) from behind with a light source. A standard camera is then used to capture the amount of light that transmits through the 2-D area for any given condition (unsaturated to fully saturated). These images are recorded in standard RGB (red–green–blue) format, and converted into HSI (hue–saturation–intensity) format. An image or photograph can be broken down into three distinct layers of the image itself – the hue, saturation, and intensity. The hue is the wavelength of the light energy, the saturation is the bandwidth of the wavelength, and the intensity is the total energy value or the amplitude. Upon conversion into this format, information on the water content is discernable. Specific combinations of the HSI format can be used to determine the water content depending on the nature of the 2-D system and fluids. Similarly, the porous medium is calibrated via water saturation to a known percentage and a discrete value is obtained via the HSI format. The experimental design reduced the efficacy of hue and saturation as opposed to intensity; here intensity was used to create the calibration equation for the experiments.

The 2-D tank was constructed using clear 1.3 cm thick polycarbonate plates (8707K153, McMaster-Car, Douglasville, GA) for purposes of visualizing the flow process (Fig. 2). The 30.5 × 1.3 × 30.5 cm tank contains four porous plates (0660X01-B01M3, Soilmoisture Equipment Corp., Goleta, CA) along the sloped bottom of the tank, and an effluent port at the base of the slope. For experiments, the tank is fitted to an aluminum stand with an LED light source mounted on the back (36 W dimmable, natural white 61 × 61 cm, LPWD-NW6060-36, superbrightleds.com, St. Louis, MO), and a rainfall simulator (screw actuator) is mounted on top. To prevent reflective and refractive light from affecting the images collected, the excess light...
Table 2. Concentration variations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics; Suwanee River natural organic matter, SRNOM) used to create the solutions tested in this work. The middle row shows high concentrations of the constituent, the bottom row shows a moderately high amount, and the top row shows a typical natural concentration.

<table>
<thead>
<tr>
<th>Concentration</th>
<th>Citrate (mg L(^{-1}))</th>
<th>Oxalate (mg L(^{-1}))</th>
<th>SRNOM (mg L(^{-1}))</th>
<th>Tannic acid (mg L(^{-1}))</th>
</tr>
</thead>
<tbody>
<tr>
<td>Low</td>
<td>0.1</td>
<td>0.1</td>
<td>0.1</td>
<td>0.1</td>
</tr>
<tr>
<td>High</td>
<td>500</td>
<td>500</td>
<td>–</td>
<td>500</td>
</tr>
</tbody>
</table>

Figure 2. Experimental set up of the 2-D tank system.

from the LED light was blocked to ensure the transmission of only visible light through the tank.

An empirical calibration curve was created using small calibration tanks (7.6 \(\times\) 1.5 \(\times\) 8.9 cm) filled with the silica sand to multiple preset water saturation percentage points (i.e., 0, 5, 10, 20, 40, 60, 80, and 100 %). The calibration was completed in triplicate to account for potential variations in packing and ambient light pollution. A linear calibration relationship was seen between the increasing water saturation percentage points and the increasing transmitted intensity (Fig. 3); this trend was also observed in the work of Uyusur et al. (2016). This linear relationship and slope equation were used to convert the intensity values into water saturation values with MATLAB (R2016a, The Mathworks Inc., Natick, MA, USA). Additionally, for each 2-D tank flow experiment, the intensity values corresponding to locations where 0 and 100 % water saturation occurred were found, and the slope from each experiment was compared to the calibration curve to ensure that the calibrations between experiments were similar.

2.4 2-D tank flow experimental design

The 2-D tank was secured to the stand prior to packing to minimize jostling and to reduce sand movement, thus decreasing the likelihood of heterogeneity. A packing device, a Y-shaped sand loader containing a piece of cloth, was then affixed to the top of the tank and was used to pour the sand into the tank. It was filled with two tank volumes of graded sand that conform to ASTM (American Society for Testing and Materials) C778 standards (US Silica, Ottawa, IL). The cloth was then removed to create a uniform loading of sand within the tank. The second tank volume of sand allows for the homogeneous packing of the tank to a uniform bulk density of 1.50 g cm\(^{-3}\). The US Silica product data sheet described the size of the ASTM graded sand using standard USA sieve mesh sizes from 16 – Pan (US Silica, 1997) (Fig. 4). The packing device and extra sand were removed from the top of the tank, which was then gently tapped to create an even sand surface. A cover was secured around the apparatus to block refractive and reflective light from the LED source and to ensure that only transmitted light was seen in the images. Specifically, 1 cm of the top portion of the tank and sand was covered; this dimension is assumed as part of the uniform wetting front for the data presented here.

All tank flow experiments were done in replicate, with data presented in this work derived from the averages of the replica, and the images presented from a single experiment representing the system’s characteristics. The secondary experimental images are available for viewing in the Appendix.
Table 3. A. R. Pales et al.: Preferential flow systems amended with biogeochemical components

<table>
<thead>
<tr>
<th>Solution</th>
<th>NaCl (HNS)</th>
<th>Citrate (0.1 mg L$^{-1}$)</th>
<th>Oxalate (0.1 mg L$^{-1}$)</th>
<th>Organics (SRNOM) 10 mg L$^{-1}$</th>
<th>Wetting front (cm)</th>
<th>Average contact angle ($\theta$)</th>
<th>Average surface tension ($\gamma$)</th>
<th>Time (s)</th>
<th>Average velocity (cm s$^{-1}$)</th>
<th>Average depth of fully formed fingers (cm)</th>
<th>Average length of fingers (cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>64.5 ± 2.6A</td>
<td>75.8 ± 0.5A</td>
<td>70.2 ± 1.8B</td>
<td>63.7 ± 1.4B</td>
<td>1.60 ± 0.5B</td>
<td>67.1 ± 2.6B</td>
<td>66.1 ± 1.8B</td>
<td>600</td>
<td>2.5B</td>
<td>0.082 ± 0.002B</td>
<td>0.78 ± 0.029B</td>
</tr>
<tr>
<td></td>
<td>72.7 ± 2.6B</td>
<td>70.2 ± 1.6B</td>
<td>71.9 ± 1.4B</td>
<td>70.0 ± 1.3B</td>
<td>1.60 ± 0.5B</td>
<td>67.1 ± 2.6B</td>
<td>66.1 ± 1.8B</td>
<td>600</td>
<td>2.5B</td>
<td>0.082 ± 0.002B</td>
<td>0.78 ± 0.029B</td>
</tr>
<tr>
<td></td>
<td>54.4 ± 2.6B</td>
<td>70.2 ± 1.8B</td>
<td>70.2 ± 1.6B</td>
<td>70.0 ± 1.3B</td>
<td>1.60 ± 0.5B</td>
<td>67.1 ± 2.6B</td>
<td>66.1 ± 1.8B</td>
<td>600</td>
<td>2.5B</td>
<td>0.082 ± 0.002B</td>
<td>0.78 ± 0.029B</td>
</tr>
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<td></td>
<td>61.7 ± 2.6B</td>
<td>70.2 ± 1.8B</td>
<td>71.9 ± 1.4B</td>
<td>70.0 ± 1.3B</td>
<td>1.60 ± 0.5B</td>
<td>67.1 ± 2.6B</td>
<td>66.1 ± 1.8B</td>
<td>600</td>
<td>2.5B</td>
<td>0.082 ± 0.002B</td>
<td>0.78 ± 0.029B</td>
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The experimental exudate and soil component solutions were individually pumped into the 2-D tank for each experiment. A Cole Parmer peristaltic pump was used for this process (pump head; Masterflex easy loader II L/S model 77200-60, Masterflex peroxide-cured silicone tubing L/S 16, Cole Parmer Instruments Co., Vernon Hills, IL) with the solutions distributed across the top of the 2-D tank by artificial rainfall (rotating screw actuator) over a 45.72 cm$^2$ area, at a constant pump rate of 10 mL min$^{-1}$ (flow velocity, i.e., the surface area averaged input flux rate, of 13.12 cm h$^{-1}$).

A Nikon CMOS D5500 DSLR camera with AF-S DX NIKKOR 18–55 mm f/3.5–5.6G VR II Lens (model: 1546) was used to image the flow every 30 s in large, fine, JPEG format, with 6000 × 4000 pixels per image. The camera was operated manually to ensure that the highest intensity within the images was less than the maximum of 255. This was also done for the calibration curve images. Upon capture, the images were imported into MATLAB for quantitative analysis. The raw RGB formatted images were converted to a HSI format. The intensity values were then used to determine the dynamic finger geometry and the vertical and horizontal water saturation profiles via MATLAB. A statistical analysis was done for the parameters of the flow experiments, utilizing a t test using JMP Pro 12 from SAS.

3 Results

3.1 Surface and interface characterizations

The time-dependent contact angles of each constituent solution at their various concentrations are displayed in Fig. 5, with the stable contact angle measurements listed in Table 3 (stable measurements taken at 90 s.). For most concentrations of the exudate solutions the contact angles are significantly lower than those of the NaCl + HNS control solution ($\theta = 64.5^\circ$ at 90 s.), the exception being the low concentration of SRNOM. Statistical analysis of the contact angle and surface tension was done via t test, and the differences are compiled in Table 3. Each constituent group displays a significant percent reduction in the contact angles of the experimental solutions against the control at time 90 s. This significant difference is illustrated through the t-test groupings displayed in Fig. 6. The SRNOM percent reduction in the contact angle values were 4% for 0.1 mg L$^{-1}$, and 30% for 10 mg L$^{-1}$. The citrate percent reductions in the contact angle values were 18% for 0.1 mg L$^{-1}$ and 29% for 50 mg L$^{-1}$. The oxalate percent reductions in the contact angle values were 15% for 0.1 mg L$^{-1}$ and 26% for 500 mg L$^{-1}$. For the tannic acid, however, the variability in the reduction in contact angle occurred regardless of the increase in concentration and averaged a 17% reduction. Significant differences can be seen in all experimental solutions, except for the low concentration of SRNOM. For the remainder of the experimental solutions, two main groups were not dependent on concentra-
The first group comprised the tannic acids, citrate, and oxalate at low concentrations that were similar to each other. The second group comprised citrate, oxalate, and SRNOM at their high concentrations that also were similar to one another. However, the low concentration of tannic acid and the high concentration of oxalate, were not significantly different from each other.

Time-dependent surface tension measurements were taken at 30 s intervals for all experimental solutions and are displayed in Fig. 7. Additionally, the stable surface tension measurements (at time 90 s) are listed in Table 3. They were used to determine the percent reduction in surface tension over time (Fig. 8). All solutions exhibited a significantly lower surface tension than the NaCl + HNS control solution (75.7 mN m$^{-1}$ at 90 s). As with the contact angle data, the differences in surface tension were not coupled directly with differences in concentration. For example, in Figs. 5 and 7, the 500 mg L$^{-1}$ citrate solution exhibited the lowest contact angle ($\theta = 46^\circ$) and the highest surface tension (73.6 mN m$^{-1}$), at a stable time of 90 s. The percent reduction in surface tension ($t$-test groupings) illustrates more specifically that the effect of the concentration variations on the surface tension is not consistent. The statistical analysis revealed two distinct groups of surface tension values—one consisting of the low concentration of oxalate and tannic acid and the high concentration of citrate and SRNOM, and the other consisting of the remainder, seen in Fig. 8. It is important to note that the percent reduction in surface tension for the experimental solutions compared to the control was small, less than 10%. The densities of the experimental solutions were also calculated and found to range minimally, from 995.5–1002.8 kg m$^{-3}$ (Table 4).
3.2 Time-dependent unstable fingering flow

The unsaturated gravity-driven flow experiments were analyzed based on (i) the number of fingers formed, (ii) the velocity of finger propagation, and (iii) the vertical and horizontal water saturation profiles. The two extreme concentrations for the plant constituents (citrate and oxalate), which were 0.1 mg L\(^{-1}\) for the lowest and 500 mg L\(^{-1}\) for the highest, were compared with the concentrations of the soil constituents, which were 0.1 to 10 mg L\(^{-1}\) for SRNOM and 0.1 to 500 mg L\(^{-1}\) for tannic acid.

In this comparison, the number of fingers formed in each experimental test solution varied slightly (1.5 to 2.5 on average) with no discernable pattern between the various constituents and concentrations (Table 3). Although a variation was observed in the wetting front depth (i.e., the nonpreferential zone of infiltration) of each solution, a relationship to the finger propagation velocity was observed in the citrate, oxalate, and tannic acid solutions. The relationship showed that the slower propagation of the fingers indicated a greater wetting front depth (Table 3), but this finding did not hold for the soil constituent SRNOM solutions. The finger length and the wetting depth of the citrate solutions at 10 min are 22.4 and 3.5 cm for the low concentration and 19.5 and 2.5 cm for the high concentration. The finger length and wetting depth of the SRNOM solutions at 10 min are 17.7 and 7.0 cm for the low concentration and 13.3 and 3.3 cm for the high concentration. The finger length and wetting depth of the oxalate solutions at 10 min are 20.2 and 3.4 cm for the low concentration and 22.2 and 2.3 cm for the high concentration. The finger length and wetting depth of the tannic acid solutions at 10 min are 19.1 and 4.3 cm for the low concentration and 25.5 and 2.5 cm for the high concentration.

3.2.1 Finger analysis

MATLAB was next used to process and analyze the vertical water saturation profiles of the main finger for each solution (Figs. 9 and 10). The NaCl + HNS control solution exhibited a substantial wetting front and a uniform water saturation distribution through the vertical finger profile (∼50 %) beyond the fingertip (∼90 %). The citrate solutions were similar in that both the 0.1 and 500 mg L\(^{-1}\) formed two fingers. However, the 0.1 mg L\(^{-1}\) citrate solution formed two long and narrow fingers, with width of 6.6 cm, with the majority of the water content located directly behind the wetting front (∼100 %). In juxtaposition, the 500 mg L\(^{-1}\) citrate solution formed two well-dispersed fingers that were 7.9 cm in width with relatively uniform water saturation profiles (∼80 %). These well-dispersed water saturation profiles characterized the oxalate solutions, with an average saturation of ∼85 % for the low and high concentrations. The 0.1 mg L\(^{-1}\) had a greater finger length, most likely because the two fingers formed in the 0.1 mg L\(^{-1}\) sample had a width of 8.4 cm, unlike the three fingers with a width of 7.1 cm in the 500 mg L\(^{-1}\) analysis. Both long and narrow fingers with widths of 7.6 cm were observed forming from the tannic acid 500 mg L\(^{-1}\) test, with the majority of the water saturation occurring behind the tip of the wetting front (∼100 %). Further, the tannic acid at 0.1 mg L\(^{-1}\) had a slightly more uniform water saturation distribution across the finger, with a width of 10.2 cm, although the majority of the saturation still occurred within the fingertip (∼75 %). Finally, SRNOM exhibited a deep wetting front and a uniform water distribu-
saturation (~85%) in the middle of the finger and a greater dispersion zone (~60%) at 0.1 mg L\(^{-1}\). At 500 mg L\(^{-1}\), a higher saturation (~100%) in the middle of the finger and a smaller dispersion zone (~75%) were observed.

4 Discussion

4.1 Infiltration processes

The abrupt difference in the vertical and horizontal water saturation distribution profiles of the fingers that displayed high water saturation behind the wetting front and dry porous media ahead of the wetting front (Figs. 9–12) is related to the soil water sorptivity (Philip, 1955; Parlange, 1971a) as it induced the flow of water in porous media under various contact angles (Wallach et al., 2013). The interplay between the resistance to wetting resulting from the contact angle at the wetting front together with saturation overshoot and wetting front propagation is visualized by the vertical and horizontal water saturation distribution profiles that demonstrated in most cases the fingered flow with saturation overshoot (Figs. 9 and 10) and decrease in contact angle (Figs. 5 and 6) of all the systems tested compared to the control infiltration experiment.

In the initial phase of the infiltration process in dry porous media, the wetting front diffuses through the porous medium as the capillary forces dominate the gravity forces. The wetting front is wetting the sandy porous media, making it quite wet or moist, resulting then in a contact angle close to zero. Afterwards, as the capillary forces and the gravity forces assume an equal status, the wetting front propagates downward as a traveling wave. An abrupt wetting front is then generated with a high level of water saturation, which causes the development of an unstable wetting front that in turn causes the formation of fingered flow when small heterogeneities are encountered (which is inevitable, even in a practically homogeneous medium). A higher (advancing) contact angle is located at the wetting front that propagates in the porous medium and a lower (receding) contact angle is present in the now-wetted porous medium (Morrow, 1976). The disproportion between the inward and outward fluxes at the finger tip increases, which results in the development of the overshoot saturation. Our experimental results, which include the vertical water distribution profiles, the visualization of the overshoot saturation, and the wetting front velocity measurements, support these findings (Figs. 9 and 10; Table 3).

4.2 Redistribution processes

After the initial infiltration process the redistribution within the fingered flow differs depending upon the solution chemistry and concentration. A noticeable effect of the constituents and concentrations upon the water distribution was observed and can be attributed to the different matric potentials within the fingers (DiCarlo, 2004; Glass et al., 1989c,
Although this increase in the matric potentials causes “saturation overshoot” (i.e., resulting in saturated fingertips), a reduced matric potential enhances the fluid movement in the porous media which results in a more uniform water saturation distribution in the fingers (Figs. 9–12) (DiCarlo, 2004; Glass et al., 1989c, d; Wallach et al., 2013). The occurrence of “saturation overshoot” at the fingertips occurs as the result of the fingering flow failing to overcome the pressure potential to ensure the downward flow (as seen in Figs. 9–12), most notably in the citrate and tannic acid flow systems. It is possible, however, to use data from the fundamental contact angle and surface tension analysis of the solutions in conjunction with the “saturation overshoot” observations to further illustrate how the wettability changes the flow patterns and the water content distribution of the finger saturation profiles. An increase in wettability causes an increase in solution sorptivity due to the reduction in the matric potential required for the solution to enter the pore spaces. These pressure changes result in variations in the water saturation distributions determined elsewhere. Specifically, Wallach et al. (2013) found that for systems with higher contact angles, the air-entry pressure was greater, and thus the fingering flow was most likely to develop a more highly saturated fingertip (DiCarlo, 2004; Glass et al., 1989c, d; Wallach et al., 2013). Similar results were determined in this present analysis in which the higher concentration solutions exhibited lower contact angles (except for tannic acid) with more uniform saturation distributions. A comparison between the low and high concentrations for citrate and tannic acid clearly indicated the presence of “saturation overshoot” at lower concentrations when the contact angle was greater. At higher concentrations, however, the solution saturation exhibited a greater uniformity with a more substantially reduced contact angle. However, these conclusions cannot be applied to oxalate and SRNOM, which at both concentrations exhibited uniform saturations, illustrating that factors such as flow velocity (Wallach et al., 2013) clearly affect the finger geometries and development. Additionally, with limited comparable plant exudate studies, comparisons can be drawn to existing studies upon the effects of surfactants in soil systems since plant exudates act as organic surfactants in the rhizosphere. It was determined that the simulated plant exudates and the soil constituent solutions exhibited behaviors similar to those delineated in the studies of Bashir et al. (2011) and Henry et al. (2002), which demonstrated that the solute concentration, ionic strength, and pH
affected not only the surface tension but also the contact angle.

### 4.3 Finger geometry and capillary potential

Comparisons should be made between finger geometry and capillary potential by using the Young–Laplace equation, and not individually with contact angle. The reason is that tannic acid did not show a difference in contact angle between low and high concentrations, but it showed a large difference in surface tension and in finger geometry. The capillary pressure calculation would capture that difference. The Young–Laplace equation can be used to express capillary pressure at the pore scale as a function of surface tension and contact angle. This equation is expressed as follows:

\[ P_c = \frac{2\gamma \cos \theta}{r} \]  \hspace{1cm} \text{(3)}

where \( P_c \) is for the capillary pressure, \( \gamma \) and \( \theta \) are the surface tension and contact angle of a solution, respectively, and \( r \) is the radius of the pore size of the medium (Lord et al., 1997).

Modeling approaches have been developed to assess the relationships between particle sizes and pore size distributions in porous media constituted by multicomponent particles (Assouline and Rouault, 1997). By taking a multicomponent pack of an infinity of particles described by a particle size distribution (PSD), \( f(r) \), which satisfy the dense random packing condition (Wise, 1952), four particles of radii \( r_1, r_2, r_3, \) and \( r_4 \) that are in contact form an empty void space in a porous medium. The volume of this void is approximated by the volume of the osculatory sphere of radius \( r_V \) (Soddy, 1936), which can be used as an estimated value of \( r \), the radius of the pore size of the medium, and expressed as follows:

\[ r_V^{-1} = \frac{\sum_{i=1}^{4} \left( \frac{1}{r_i} \right) + \sqrt{3} \sqrt{\sum_{i=1}^{4} \frac{1}{r_i^2}} - 2 \sum_{i=1}^{4} \left( \frac{1}{r_i} \right)^2}{2}. \]  \hspace{1cm} \text{(4)}

The examination of the relationship between the finger width and the capillary pressure of fully formed fingers resulting from infiltration of water in US Silica C778 ASTM graded sand for the tested solutions showed that the finger width tended to increase as the capillary pressure decreased (Fig. 13). The observed weak correlation in the finger width and capillary pressure relationship indicates that the capillary pressure difference across the water–air interfaces may to a certain degree influence the propagation of the wetting front.
Figure 11. Multigraph comparison of the finger width profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and low concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger at its full length. The location of the horizontal water saturation profile analyses and widths are measured at 25, 50, 75, and 90 % of the total fingers length.

Figure 12. Multigraph comparison of the finger width profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and high concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger at its full length. The location of the horizontal water saturation profile analyses and widths are measured at 25, 50, 75, and 90 % of the total fingers length.

and development and growth of fingers, as well as the sorptivity. As previously stated by Wallach et al. (2013), “this effect can be mainly related to the soil water sorptivity (Philip, 1955; Parlange, 1971[a]) and its role on the spontaneous and forced water flow in the pores at different contact angles”.

4.4 Hydrodynamic scaling in porous media of finger dimensions

Unstable fingering flow geometries have been analyzed under various settings, especially that of Parlange and Hill (1976), who developed equations to calculate the width of a finger in an air–water system by including the sorptivity, and Glass and Nicholl (1996), who modified the equation to conform in air–water systems. This equation is expressed as follows:

\[
d_c = \pi \frac{S^2}{2K_s (\theta_s - \theta_i)} \left( \frac{1}{1 - q_s/K_s} \right),
\]

where \(d_c\) is the minimum finger width, \(S\) is the sorptivity, \(\theta_s\) is the saturated water content, \(\theta_i\) is the initial water content, \(q_s\) is the flux, \(K_s\) is the saturated hydraulic conductivity, and \(\pi\) is a constant for a 2-D system (Glass et al., 1991; Wallach et al., 2013). Scaling of fluid flow in porous media was established by Miller and Miller (1956). Hydrodynamic scaling in porous media directed to unstable wetting front and fingered flow may be utilized to measure the finger width. Scaling of the equation advanced by Parlange and Hill (1976) to calculate the finger width can be performed by using the Miller and Miller scaling theory (1956). The resulting scaling equation can be applied to the width of fingers and is expressed
Figure 13. Finger width vs. capillary pressure of fully formed fingers resulting from infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), plant exudates (citrate and oxalate), and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM).

as follows:

\[
d_s = \frac{\rho g \lambda}{\sigma_{gl}},
\]

(6)

where \( \rho \) is liquid density, \( g \) is the gravitational constant, \( \lambda \) is the characteristic media length scale, \( \sigma_{gl} \) is the gas–liquid interfacial tension, \( d \) is the finger width, and \( d_s \) is the scaled finger width (Glass and Nicholl, 1996). This scaling equation has been utilized to estimate the finger widths based on the fluid properties and porous media characteristics (Selker and Schroth, 1998). Then, we evaluated the finger widths measured in our experiment by executing a scaling based on the density of the plant exudate and soil component solutions compared with the control (NaCl + HNS) solution, the gas–liquid interfacial tension of the plant exudate and soil component solutions compared with the control (NaCl + HNS) solution, and the coupling of both the density and gas–liquid interfacial tension of the plant exudate and soil component solutions compared with the control (NaCl + HNS) solution (Table 4). Scaling results demonstrated that the fluid density, the gas–liquid interfacial tension, and the coupling of fluid density and gas–liquid interfacial tension did not have a significant effect on the scaling discrepancies of the finger widths. Scaling discrepancies of the finger widths remained similar between the experiments rather that explicating the mechanisms responsible for the differences in finger width (Table 4). The reason for these unchanged discrepancies in the scaling of the finger width can be related to the consistency of the contact angle among the experiments to be scaled when utilizing the Miller and Miller scaling theory (Selker and Schroth, 1998). Culligan et al. (2005) also revealed that soil sorptivity is governed by \((\cos \theta)^{1/2}\) while other studies showed the opposite (Philip, 1971). Recently, an expansion of the Miller and Miller scaling theory to scale sorptivity by contact angle was introduced by Wallach and Wang (2013). Their findings showed that the Miller and Miller scaling theory can be used to scale sorptivity by the contact angle, i.e., \((\cos \theta)^{1/2}\) in the case of uniform pore media. This is the case here, as our experiments are performed in homogeneous and uniform sandy porous media in which the fingering flow phenomenon develops. Based on these conclusions, the finger width was scaled with \((\cos \theta)^{1/2}\) to include the influence of contact angle and pore dimension (Table 4) and expressed as follows:

\[
d_s = d(\cos \theta)^{1/2}.
\]

(7)

Scaling results demonstrated that the use of \((\cos \theta)^{1/2}\) does not decrease the scaling discrepancies of the finger width but increases the scaling discrepancies of the finger width (Table 4), thus proving some influence of the contact angle, through the expression of \((\cos \theta)^{1/2}\), on the formation and growth of fingers in porous media and the width of fingers, as well as providing evidence of the pore scale factor in fingering flow phenomena (Steenhuis et al., 2013).

4.5 Exudate effects

The rhizosphere is extremely complex, and interactions between the components are typically compounding, as comparisons of the study of Zarebanadkouki et al. (2016) to those of Walker et al. (2003) and Nardi et al. (2000) indicate. Root exudates have been shown to change soil physicochemical properties (Nardi et al., 2000; Walker et al., 2003) and “mucilage, a polymeric gel that is exuded by most plant roots, is believed to be one of the main factors influencing the rhizosphere hydraulic properties” (Zarebanadkouki et al., 2016). Specifically, in the broad approach used to elucidate the entire root system, Walker et al. (2003) found that the root exudates compounded with mucilage under certain circumstances exhibited a stabilizing effect on the rhizosphere (i.e., the stabilization of the soil structure near the roots). Naveed et al. (2017) demonstrated that exudates from barley roots may disperse soil while exudates from maize roots and chia seed exudates may increase soil stability around roots or seeds. While the exudates lowered the surface tension of the soil pore water, similar to what the authors determined in this research (Figs. 7 and 8), the mucilage acted as a glue, bonding soil aggregates to the root sheaths and creating a water holding space around the roots as the surrounding soil continued to dry (Walker et al., 2003). Exudates, apart from the mucilage component, ultimately exert the opposite impact on flow through the porous media. Exudates increased the mobility of the fluid through porous media as illustrated in Figs. 9–12. Specifically, in their study of the effects of plant mucilage and phospholipids on the physical and chemical properties of soil, Read et al. (2003) observed a decrease in the surface tension of the soil water brought about by very
small concentrations of phospholipid surfactants and exudate organic acids (Read et al., 2003). The simplicity of analyzing solely the effects of exudates, as shown in Figs. 5–8, is beneficial in understanding the separate components of the rhizosphere as they exist (i.e., unconfounded by the rest of the multiple components). The increased soil wettability and thus mobility of the soil solution due to the presence of biogeochemical compounds need to be further studied in order to elucidate the hydrological processes and the transport of contaminants in the rhizosphere and the vadose zone.

4.6 Imaging capabilities

The recent surge in the development of visualization and modeling capabilities, specifically related to 2-D tanks, has been instrumental in studies attempting to elucidate rhizosphere systems and root zone development and characterization in situ (Carminati et al., 2016). These new capabilities, paired with current biological understandings, have yielded a novel understanding of the entire plant–root–soil–water system. However, even with such an acceleration of research, the specific distribution and paths that the fluid takes from the soil matrix into and through the plant itself remain unknown (Carminati et al., 2016). As stated by Carminati et al. (2016), “Coupling these measurements with imaging techniques that allow visualization of the root architecture and the structure and moisture of the rhizosphere could be the ultimate experiment to measure the rhizosphere properties.” The analysis presented here clearly indicates the effectiveness of combining 2-D tank systems with imaging techniques such as LTM to furthering understanding of high spatial and temporal fluid distribution and moisture gradients in the rhizosphere directly under the influence of plant roots. The increase in sensor sensitivity, particularly of matric potential sensors or pressure transducers, will be of great value in acquiring additional insight into the mechanisms occurring in the rhizosphere. As new imaging technology of soil and rhizosphere systems are developed, these technologies may be coupled with the light transmission method to study flow and transport in porous media regulated by plants and microbes. The light transmission method may also be used to support research on biological behavior and influences on flow and transport in natural porous media, as this research endeavor “will require the development of more realistic models, and additional data associated with the physical, chemical, and microbial characteristics of microenvironments in real porous media” (Baveye and Darnault, 2017).

5 Conclusion

This paper presents research on the influence of plant exudates and soil components on the infiltration process and preferential flow phenomena in soil, particularly on wetting front instability and fingered flow in unsaturated and homogeneous sandy porous media. Dynamic 2-D tank flow experiments were coupled with the unique light transmission method in order to provide a novel analysis of the influence of biogeochemical compounds on the infiltration process and wettability in a porous medium. This unique approach makes it possible for the rapid and high-resolution quantification of flow patterns and dimensions and fluid saturation profiles in porous media. Overall, solution chemistry and concentration of plant exudates and soil components were observed to exert a significant effect on the interactions between fluids and solid surfaces, and on the resulting infiltration process, finger water saturation profile, and finger width. Our findings also establish the need to consider the contact angle expressed as \((\cos \theta)^{1/2}\) when using the Miller and Miller (1956) scaling theory for the scaling of flow in porous media. The visualization and quantitative method and data produced here provides the basis for future analysis of the rhizosphere processes and to further our understanding of their impacts on soil hydrological processes, such as the effects of rhizosphere biophysics and biochemical compounds on soil moisture, infiltration, and drainage. Novel technological and methodological approaches in hydrology are essential to advancing our understanding of soil–water–plant systems. The results of our research will also be of use in increasing the effectiveness of agricultural practices related to irrigation application and engineering systems for soil water management.

Data availability. Research data used in this study can be requested by contacting the corresponding author.
Figure A1. Second tank experiment data set. Multigraph comparison of the dynamic vertical profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and low concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger and the vertical water saturation profile analysis over time.
Figure A2. Second tank experiment data set. Multigraph comparison of the dynamic vertical profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and high concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger and the vertical water saturation profile analysis over time.
Figure A3. Second tank experiment data set. Multigraph comparison of the finger width profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and low concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger at its full length. The location of the horizontal water saturation profile analyses and widths are measured at 25, 50, 75, and 90% of the total fingers length.

Figure A4. Second tank experiment data set. Multigraph comparison of the finger width profiles of infiltration of water in US Silica C778 ASTM graded sand for control (NaCl + HNS), and high concentrations of plant exudates (citrate and oxalate) and soil components (tannic acid and organics: Suwanee River natural organic matter, SRNOM). The images are of the main finger at its full length. The location of the horizontal water saturation profile analyses and widths are measured at 25, 50, 75, and 90% of the total fingers length.
Competing interests. The authors declare that they have no conflict of interest.

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